

Reformulating neural networks as mathematical programming problems

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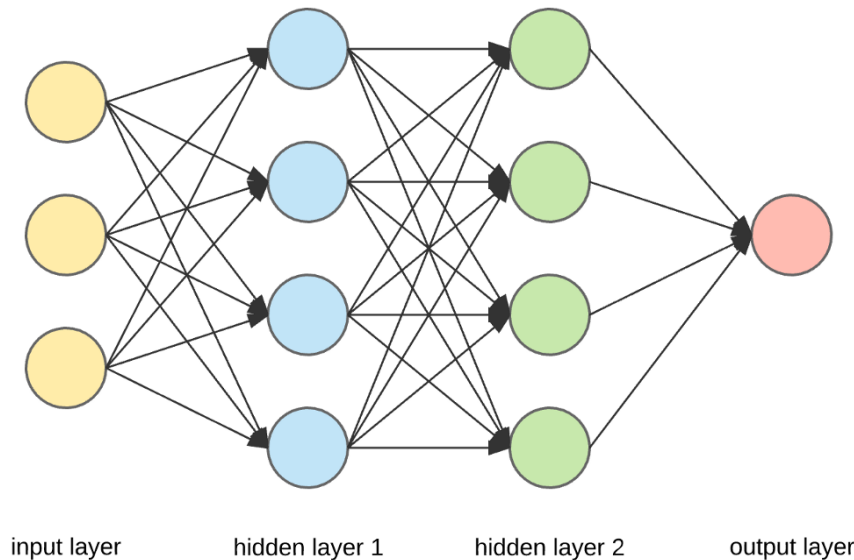
Työn saa tallentaa ja julkistaa Aalto-yliopiston avoimilla verkkosivuilla. Muilta osin kaikki oikeudet pidätetään.

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 - Feature visualization
 - Adversarial images
 - Performance analysis

Some technical notes

- Julia programming language
 - Namely Flux and JuMP libraries
- Gurobi Optimizer for 0-1 MILP optimization problems
- The code was run on a MacBook Pro with M2-processor

Training the ReLU network for digit image classification problems

- MNIST dataset: 28×28 pixel, 60 000 train, 10 000 test
- Network shape: input layer, 2 hidden layers, output layer
 - Nodes at each layer: $784 \rightarrow 32 \rightarrow 16 \rightarrow 10$
- Loss function: cross entropy
- Optimizer: ADAM(0.01) (gradient descent)
- 50 training cycles – 93,31% accuracy

0-1 MILP formulation for ReLU networks (Grimstad and Andersson, 2019)

Input layer:

$$L_{\text{in}} \leq x^0 \leq U_{\text{in}}$$

Hidden ReLU layers:

$$W^k x^{k-1} + b^k = x^k - s^k, \quad x^k, s^k \geq 0$$

$$x^k = 0 \vee s^k = 0$$

Output layer:

$$W^K x^{K-1} + b^K = x^K$$

$$L_{\text{out}} \leq x^K \leq U_{\text{out}}$$

W : weights at each layer

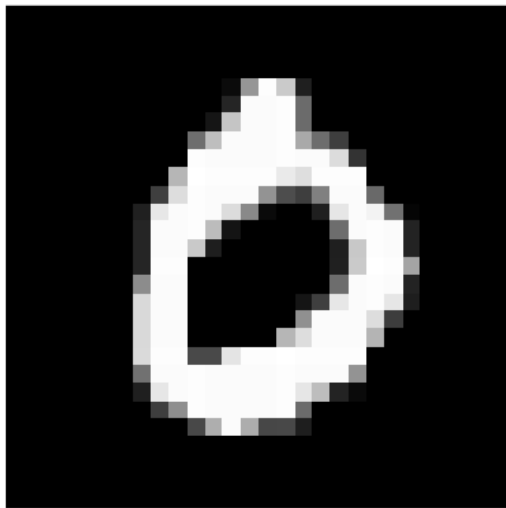
b : biases at each layer

x : node value at each layer

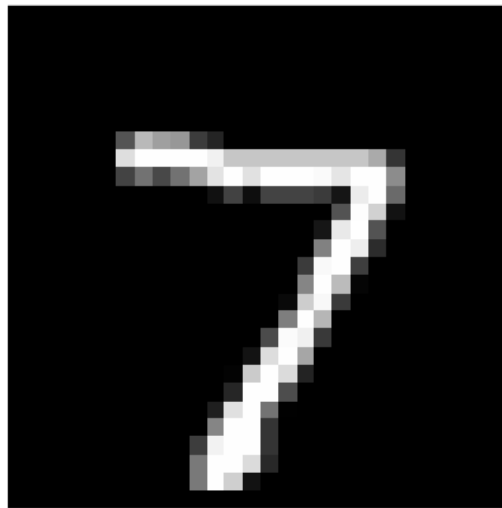
$k = \{0, \dots, K\}$: node index

Feature visualization using the surrogate

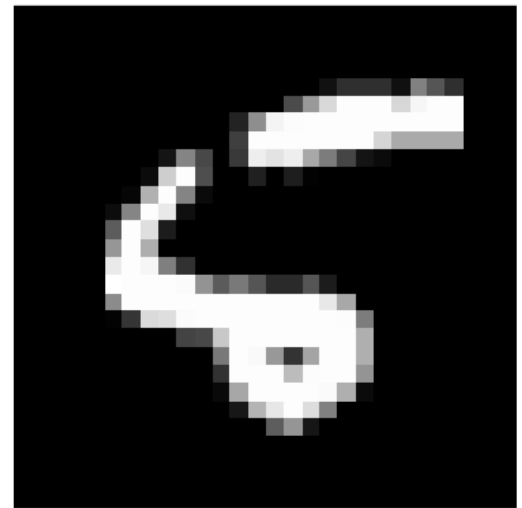
True label 0, guessed label 0



True label 7, guessed label 7



True label 5, guessed label 6

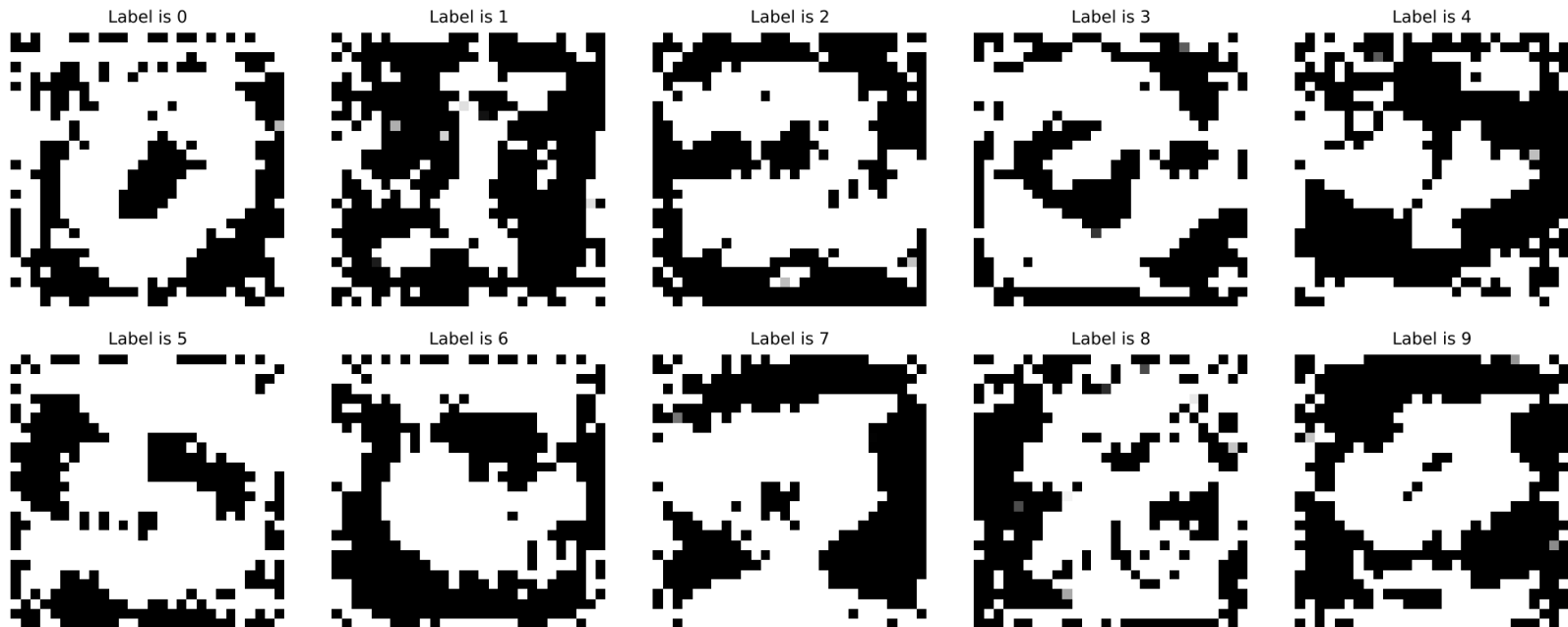


Optimizing the output value

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 - Maximize an output node corresponding to a digit

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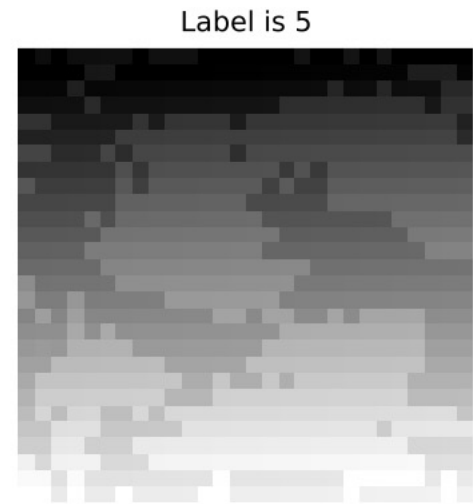
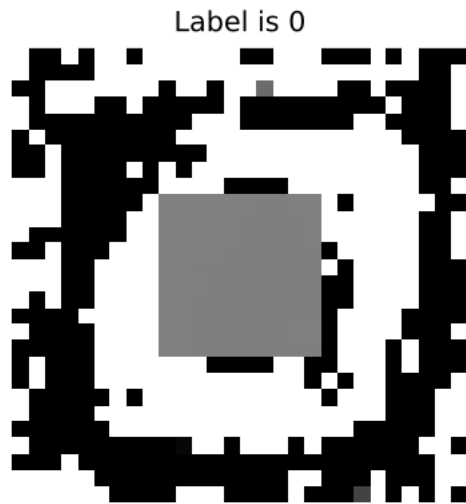


Optimizing the output value with additional constraints

- An additional objective function and constraints
 - Maximize an output node with constraints added

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- Images look “normal” to the human eye but cause misclassification
 - Added noise, a few key pixel changes, etc.
- Here, the changes to the images are optimally minimal

Building the adversarial examples

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- L^p-norm: $x = (x_1, x_2, \dots, x_n), \quad ||x||_p = \left(\sum_{1}^n x_n^p \right)^{\frac{1}{p}}$

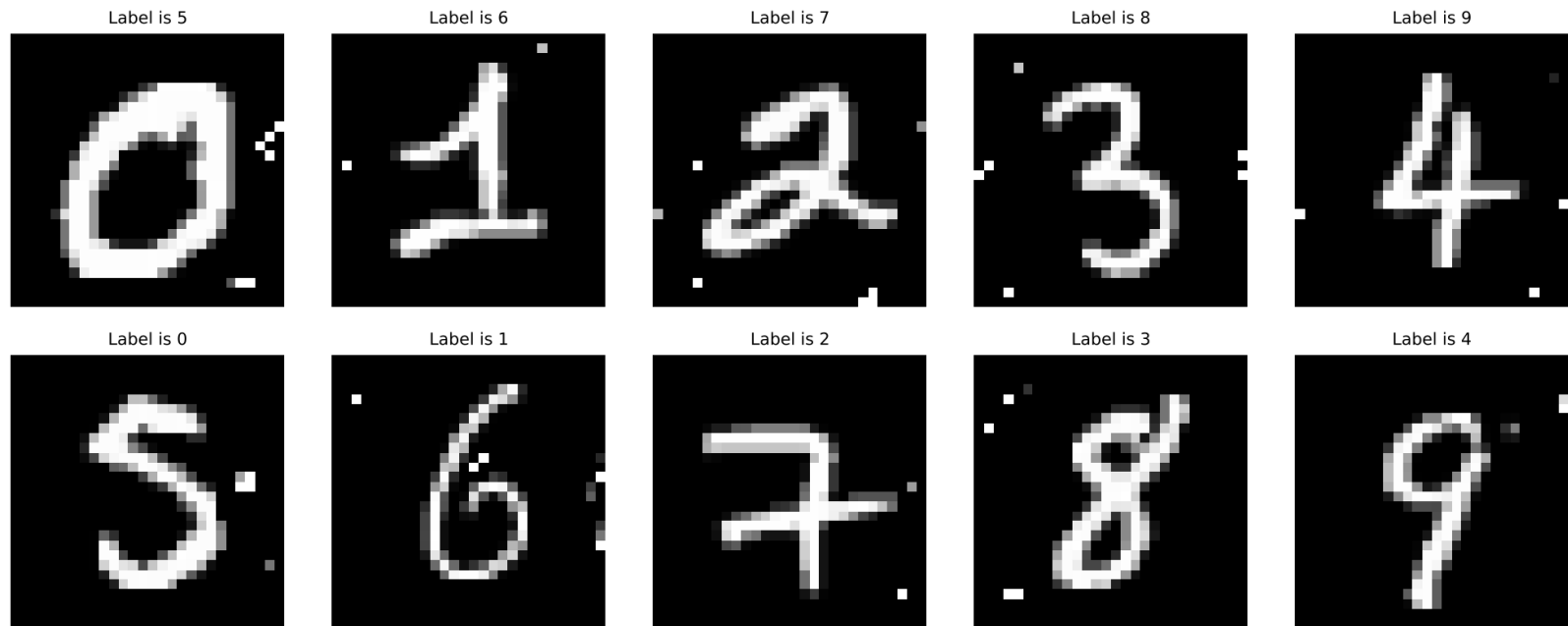
Building adversarial examples

- 1st additional constraint: $x_d^K \geq 1.2 x_j^K, \quad j \in \{0, \dots, 9\} \setminus \{d\}$
- Additional variables $d_j \geq 0, \quad j \in 1, \dots, 784$
- 2nd additional constraint: $|x_j^0 - \tilde{x}_j^0| \leq d_j, \quad j \in \{1, \dots, 784\}$
- Objective functions:

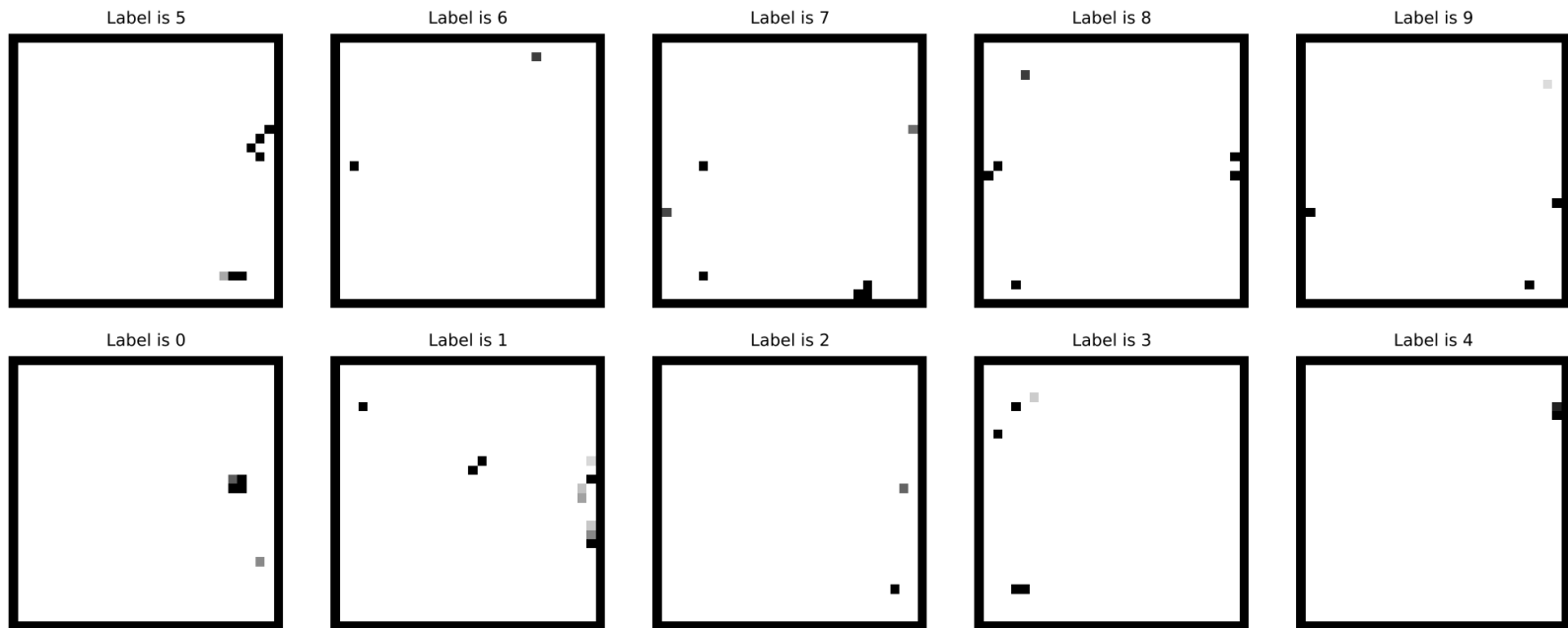
- L1-norm Min. $\sum_{j=1}^{784} d_j$

- L2-norm Min. $\sum_{j=1}^{784} d_j^2$

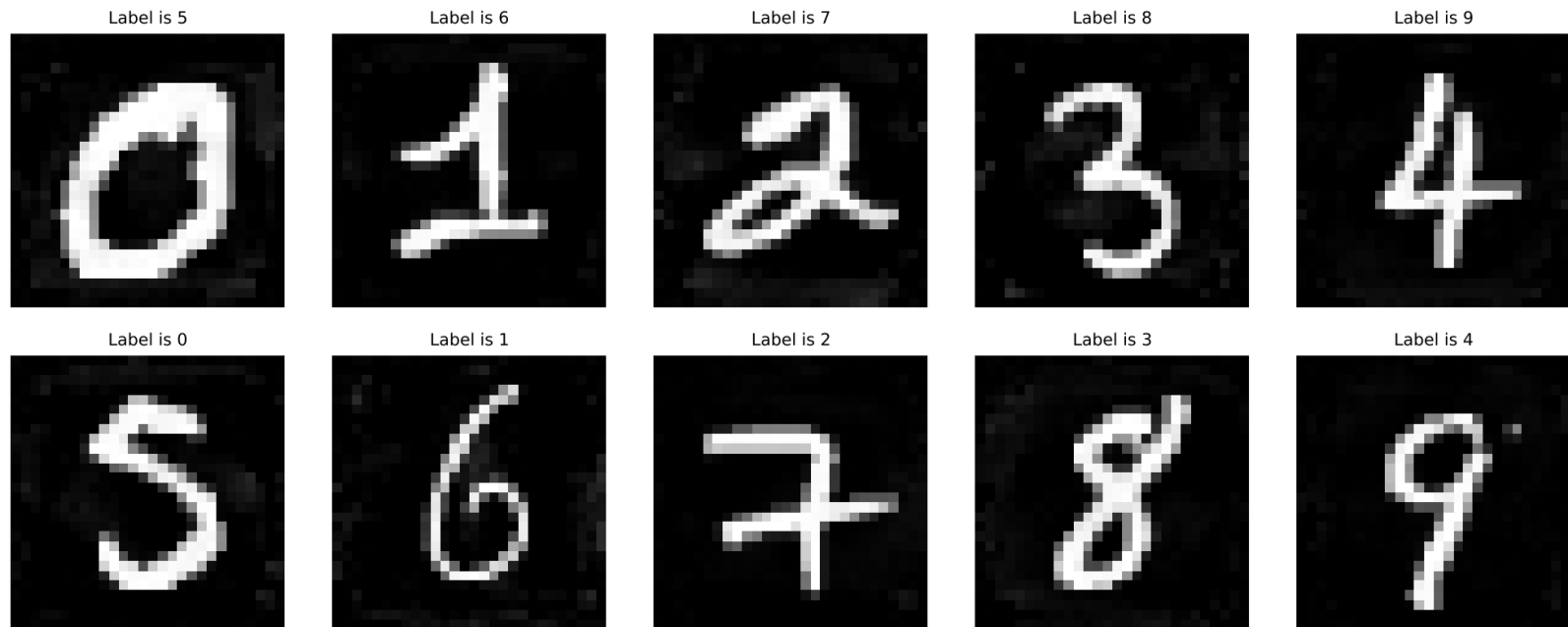
Adversarial images with L1-norm



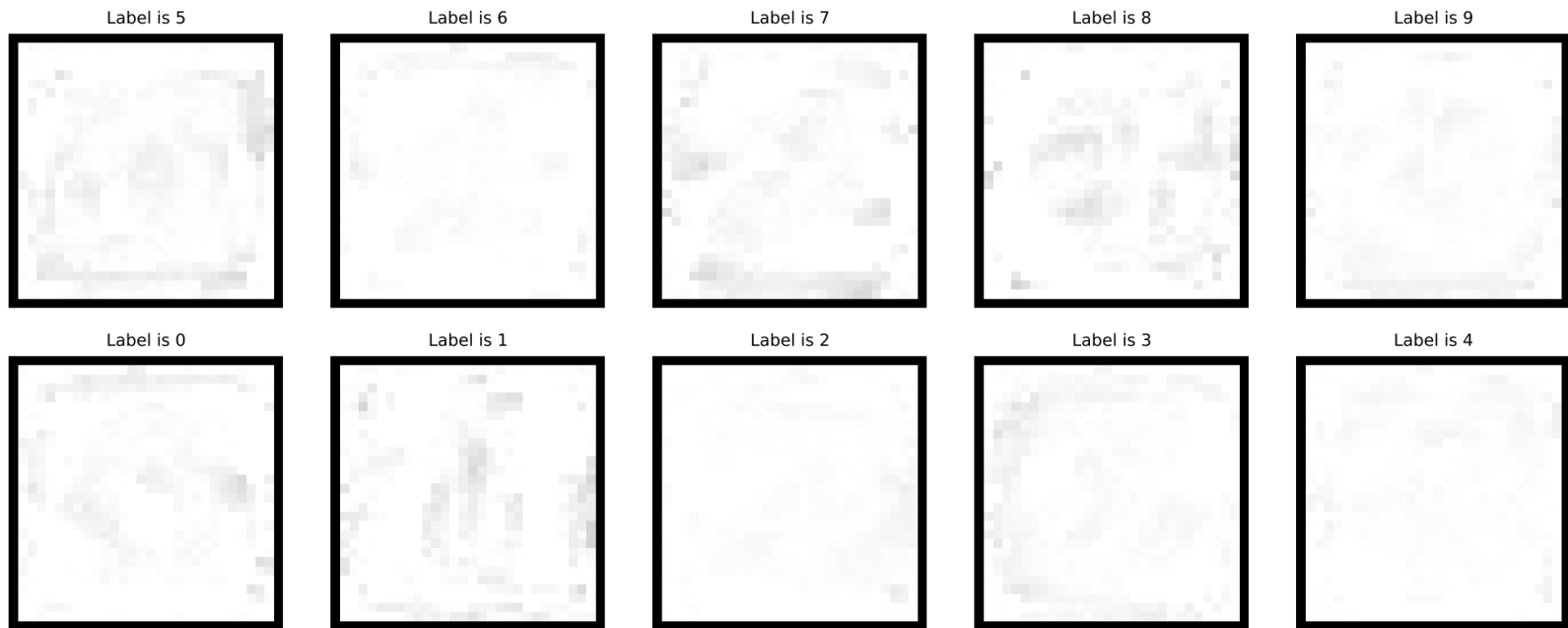
Adversarial images with L1-norm (pixel changes)



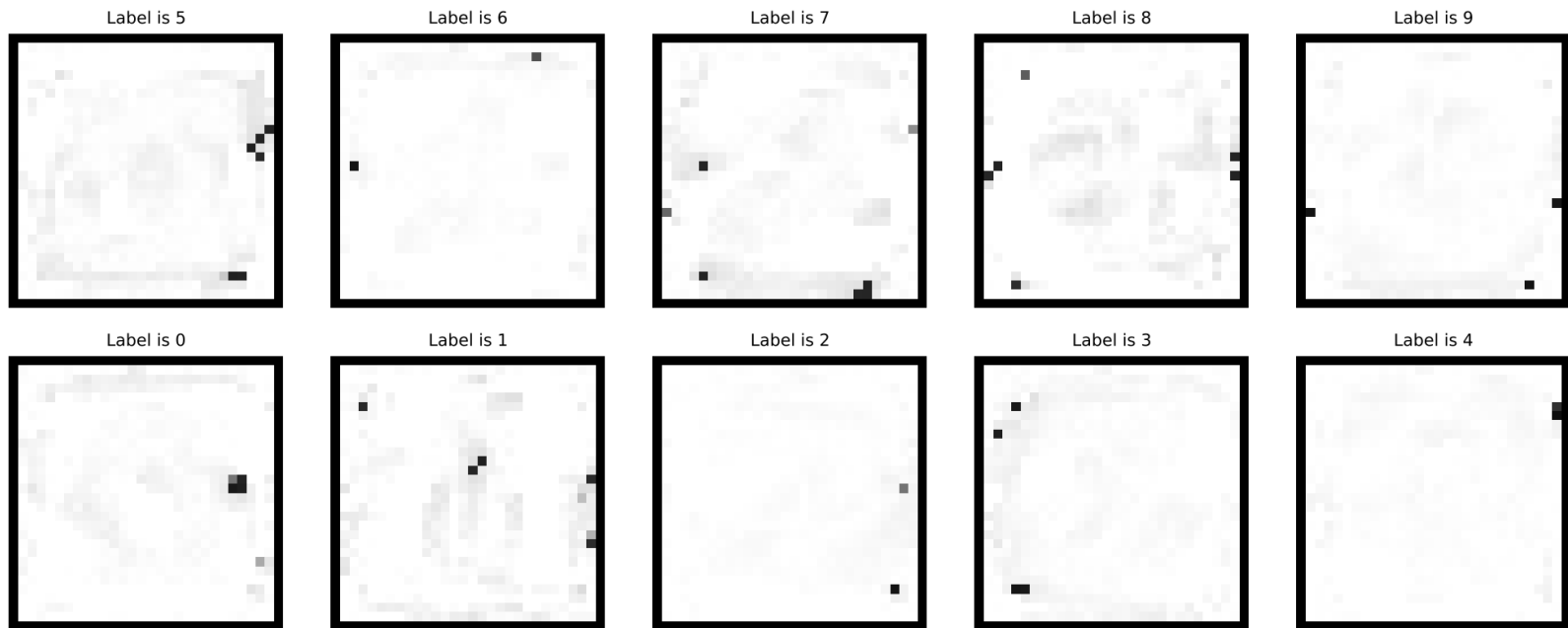
Adversarial images with L2-norm



Adversarial images with L2-norm (pixel changes)



Adversarial images (pixel changes compared)



Performance of 100 optimization cases for each application *

	Variables	Constraints	Avg. time (s)	Min. time (s)	Max. time (s)
Feature visualization	958	25760	0,0047	0,0042	0,0067
Optimal input*	958	25760	1,32	0,51	5,72
L1-norm	1742	27338	6,31	0,32	43,12
L2-norm	1742	27338	107,12	8,13	784,62

* only 10 different optimization cases available